OMRON

Confocal Fiber Displacement Sensor ZW Series

The 24×24×64-mm Sensor Head redefines the meaning of ultra-compact

EtherCAT® Standard Feature

» Robust Sensor Head Structure

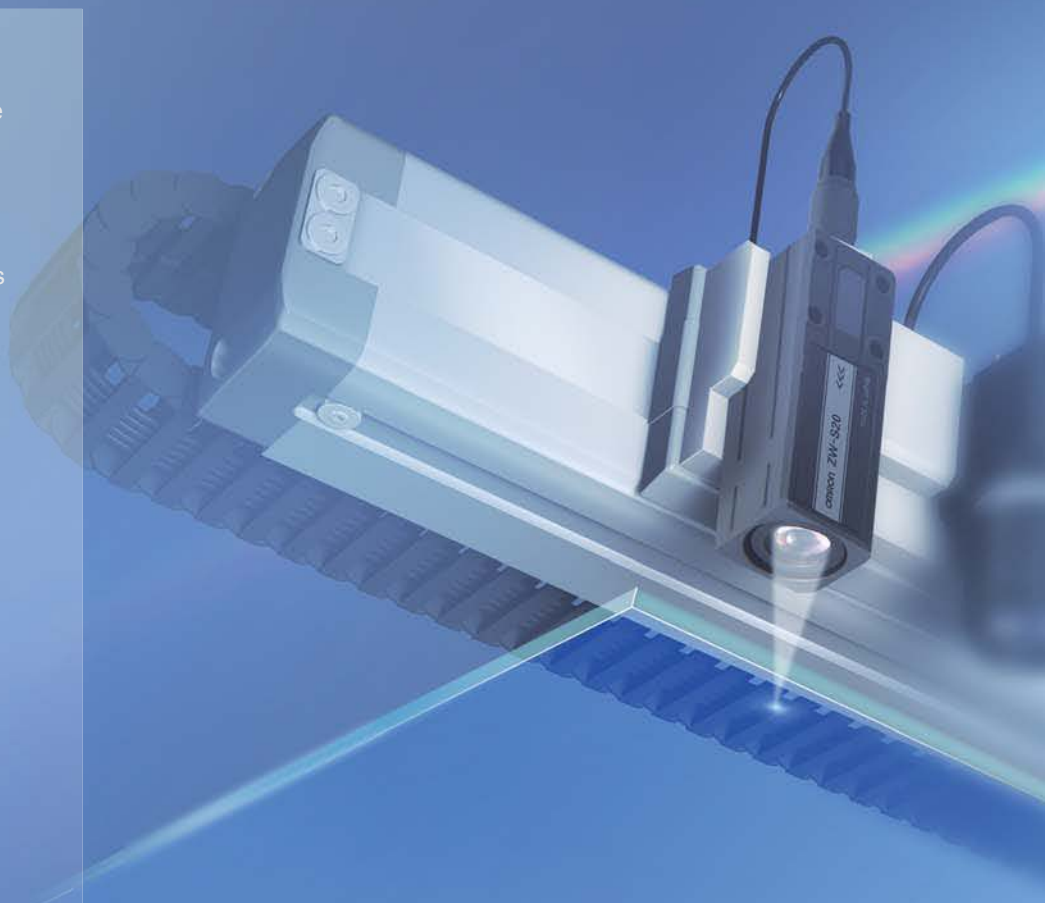
» Ultra-compact and Ultra-lightweight

» Stable Measurements for Any Material

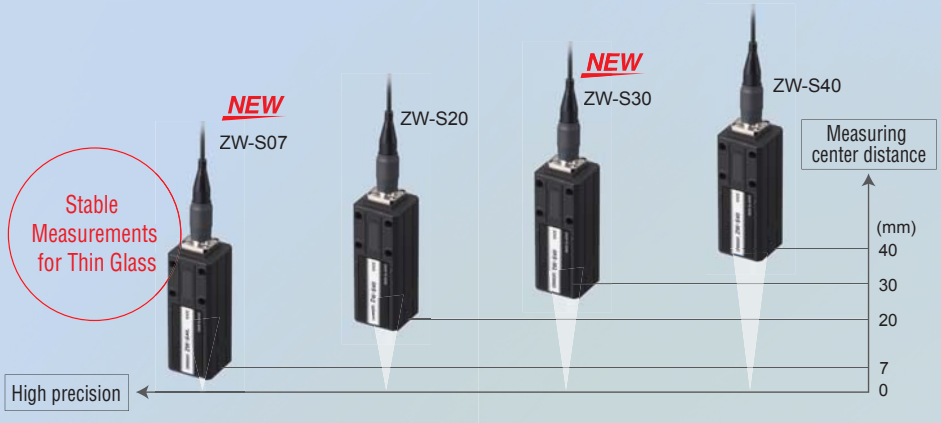
SYSMAC always in control

The Confocal Fiber Displacement Sensor beyond triangulation concepts with a new

Displacement Sensors are indispensable in non-contact measurement of heights, thicknesses, and other dimensions in machine operation control. However, building them into the system has always presented problems. The Confocal Fiber Displacement ZW Series Sensor solves these problems in ways that were not possible with traditional triangulation.
The ZW -series Sensors provide the compact size, light weight, immunity to electrical/magnetic noise, and other features to make them ideal for solving installation space problems.
And OMRON' s new confocal principle provides the measurement resolution that is needed for operation control.
The ZW Series solves the problems that came with laser triangulation, such as deviations between dif ferent materials and inclination tolerance.



A Wider Selection of Models with the Same Head Size



Expanded Communications

Standard-feature EtherCAT

P.10

Standard-feature EtherNet/IP™

NEW

-EtherCAT® is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.
-EtherNet/IP™ are the trademarks of ODVA.

that goes principle.

The Three Benefits of OMRON's White Light Confocal Principle

Ultra-compact and Ultra-lightweight

The slim design measures only 24 × 24 mm. It weighs only 105 g. This incredibly compact size could not be achieved with traditional triangulation. Any objects can be measured with the Sensor mounted perpendicular to them to save even more space.

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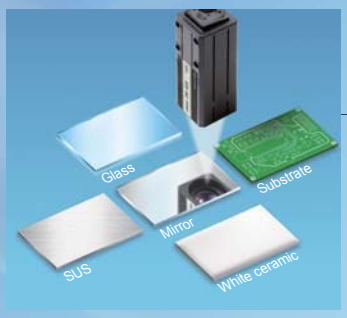

Stable Measurements for Any Material

You can measure objects of any material or color at the same position. A wide angle characteristic of ±8° enables high-resolution measurement of the position even for large objects with mirror-like surfaces without being affected by warping.

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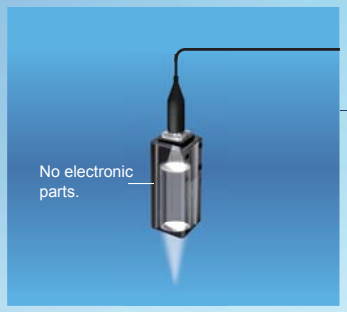

Robust Sensor Head Structure

The sensor head design maintains reliable operation in installations with electronic and magnetic noise. Devices in close proximity will not be afected by noise or heat from the sensor head or fiber cables due to their advanced design.

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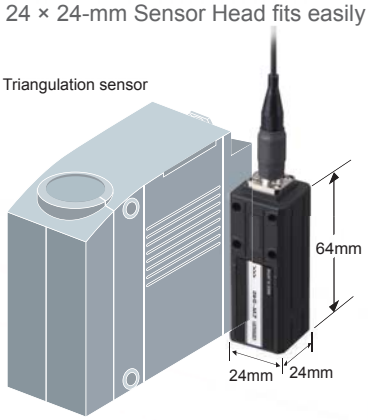
Ultra-compact and Ultra-lightweight

Utilize Narrow Spaces in Machines

The 24 × 24-mm Sensor Head fits easily into essentially any machine.



Volume ratio 1/8*

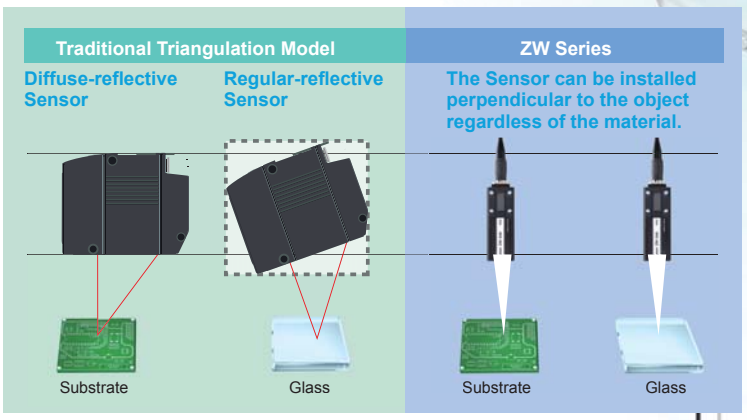
Weight ratio 1/8*

*In-house comparisons.

Mounting area Reduced to 1/7*

*In-house comparison.

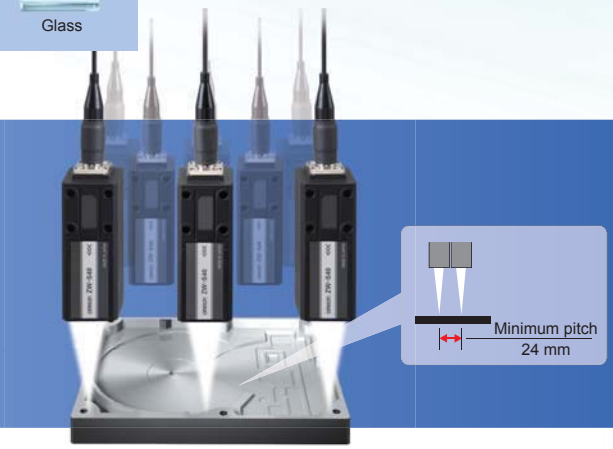
With traditional triangulation, it was necessary to use either diffuse reflection or regular reflection depending on the material. However, the confocal principle used for the ZW Series eliminates the need to change the Sensor installation even if the material changes.



Height Control of a Dispenser Nozzle

Sensor Installation in a Row with No Interference

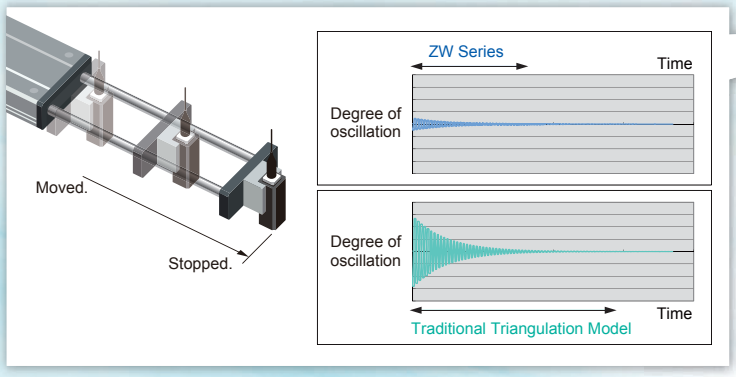
Mutual interference or space restrictions often prevent the installation of traditional triangulation sensors where necessary . Here, the compact ZW-series Sensor Heads allow you to install more sensors, in a row or otherwise.

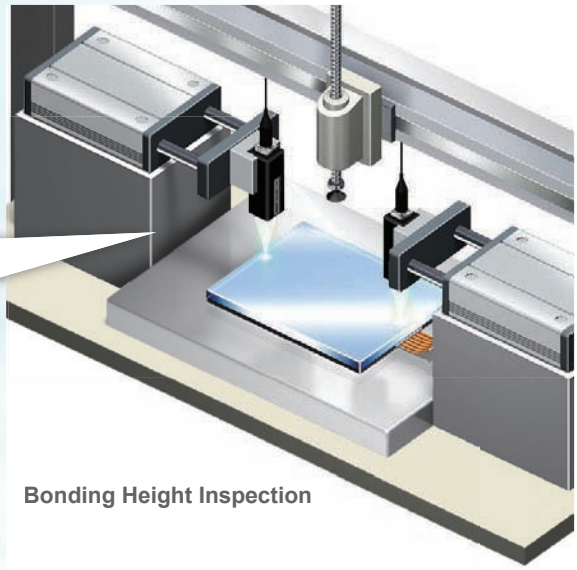


Non-contact Flatness Inspection of HDD Cases

Smooth Movement and Stopping

Using power cylinders to move sensors to measurement positions only when necessary so that the sensors do not interfere with machine motion resulting in delays in measurements while waiting for settling time if the sensor is used in this way. A ZW-series Sensor Head, however, weighs only 105 g so that measurements can be made as soon as the cylinder operation stops.

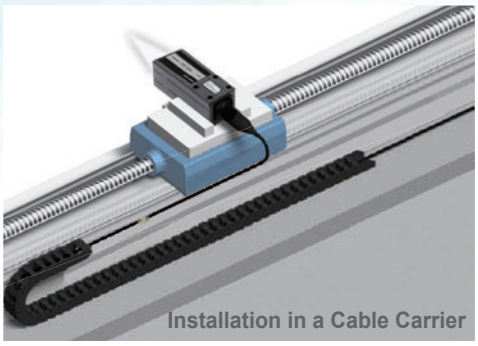


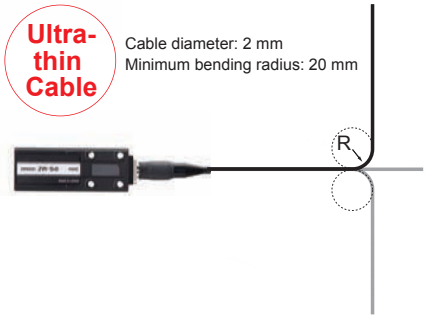

Bonding Height Inspection

Flexible Fiber Cable for Easy Installation

The Controller connects to the Sensor Head with a 2-mm-diameter Flexible Fiber Cable. The Cable has cleared a bending test consisting of 2,000,000* repetitions for reliable application on moving parts.

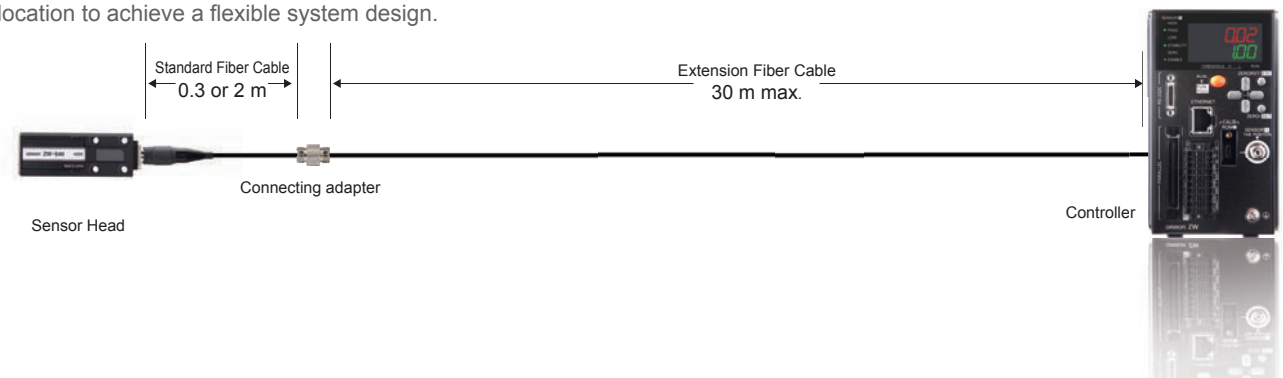
*Cable was tested with OMRON's bending test consisting of 2,000,000 bends to a 70-mm bending radius and 1,000,000 bends to a 20-mm bending radius.


Installation in a Cable Carrier



Cable Extendable to 32 m

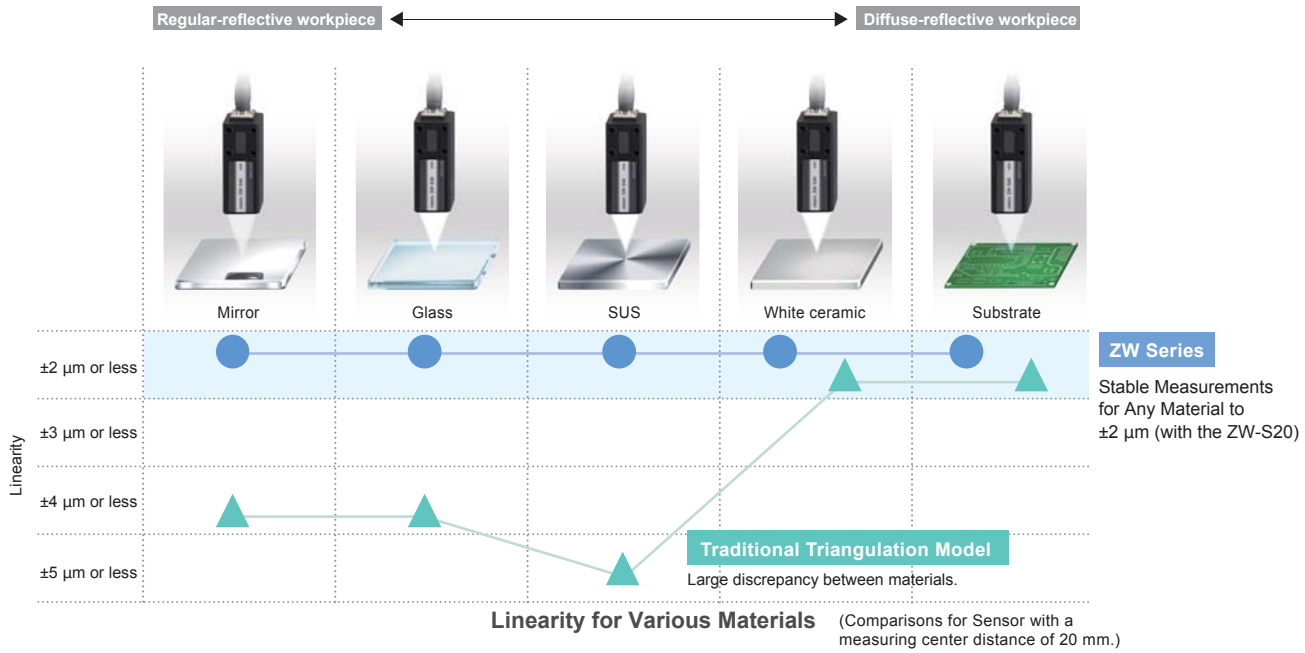
An Extension Fiber Cable can be used between the Sensor Head and Controller to extend the distance to up to 32 m. Attach the Sensor Head to a moving part and place the Controller in the control panel or other convenient location to achieve a flexible system design.



Stable Measurements for Any Material with Superior Angle Characteristic

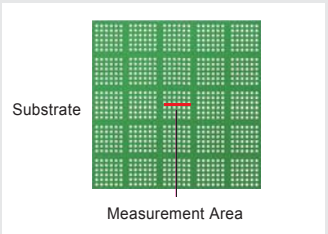
Stable Measurements from the Same Mounting Position Even for Different Materials

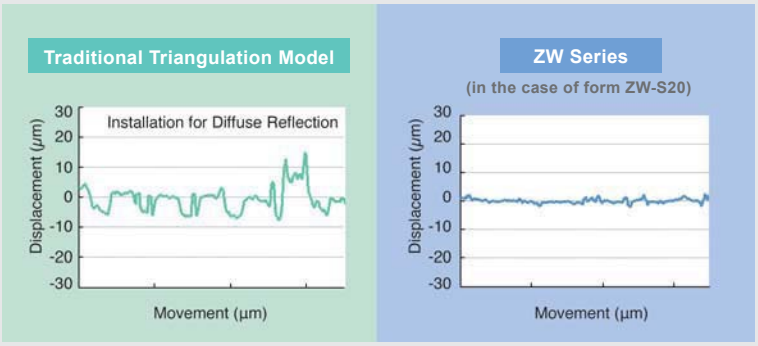
There is no need to change or tune the Sensor for each material. Even if the material changes, you can continue to achieve stable measurements with the same Sensor from the same mounting position.



Linearity for Various Materials (Comparisons for Sensor with a measuring center distance of 20 mm.)

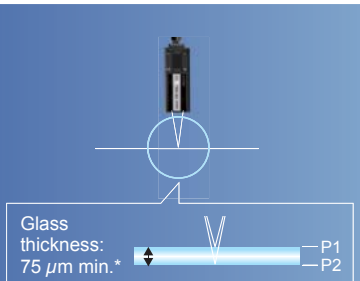
Stable Measurements across Boundaries between Materials



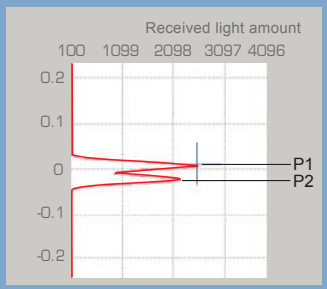


Compact Sensor Heads Provide Stable Measurements of Thin Transparent Glass

To stably measure transparent glass, the received light waveforms from the front and back surfaces of the glass must be separated. With thin transparent glass, the influence of lens aberration makes it difficult to achieve separation with compact sensor heads. Even with its compact size that saves space, the ZW -S07 stably measures transparent surface displacement on glass as thin as 75 µm, a feat not easily achieved by previous compact sensor heads.



*ZW-S07:75 µm min.
ZW-S20: 200 µm min.



Received Waveform for ZW-series Sensor

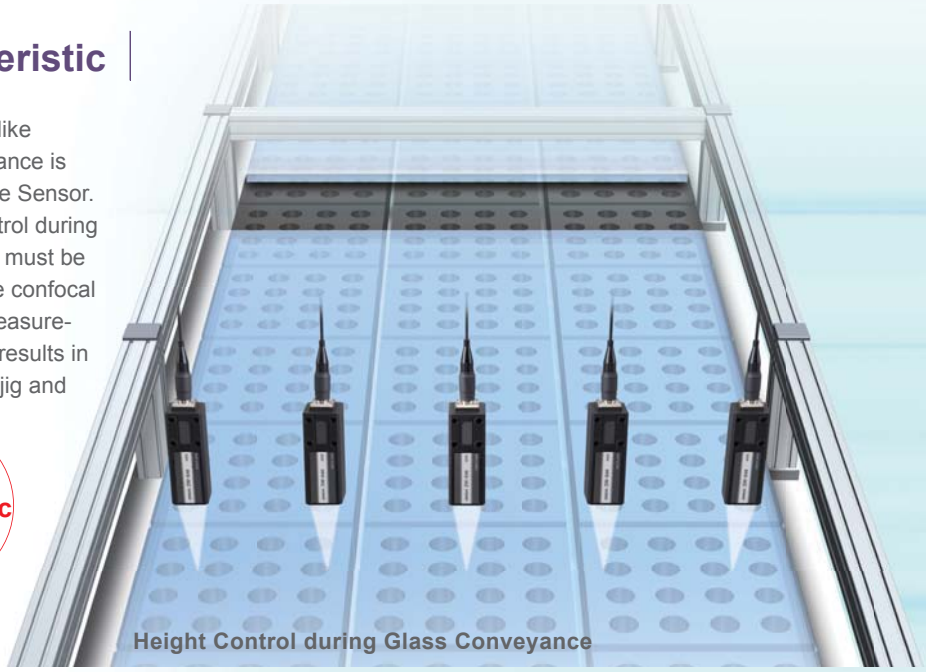
(All measurement graphs represent typical examples.)

Superior Angle Characteristic

When measuring an object that has a mirror-like surface with traditional triangulation, performance is greatly reduced depending on the angle of the Sensor. When many Sensors are used for height control during glass conveyance, the angles of the Sensors must be adjusted with high precision during setup. The confocal Sensor ZW series enables high-resolution measurements without strict angle adjustment. This results in reduction of cost and space for the adjusting jig and time for adjustment.

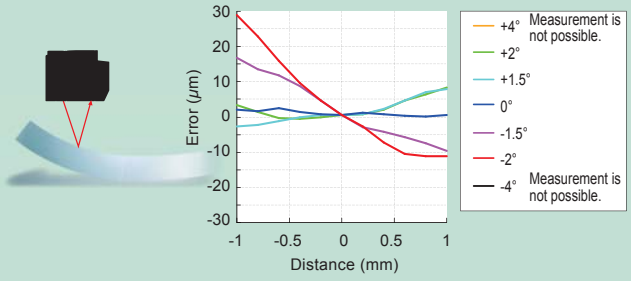
* This is not a guaranteed value. Refer to Characteristic Data (P17) for typical examples.

Angle characteristic ±8° *



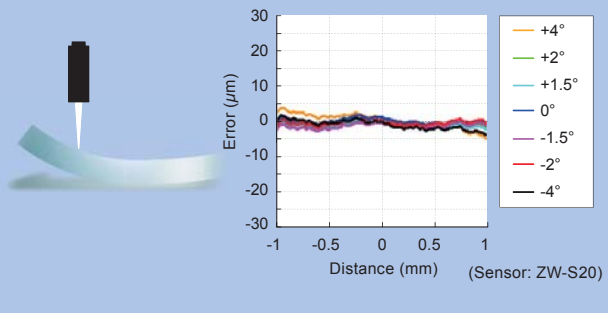
Traditional Triangulation Model

With triangulation, even if the angle is adjusted with high precision during the setup of the Sensor, stable measurement results are difficult to obtain when the measurement object is warped or inclined.



ZW Series

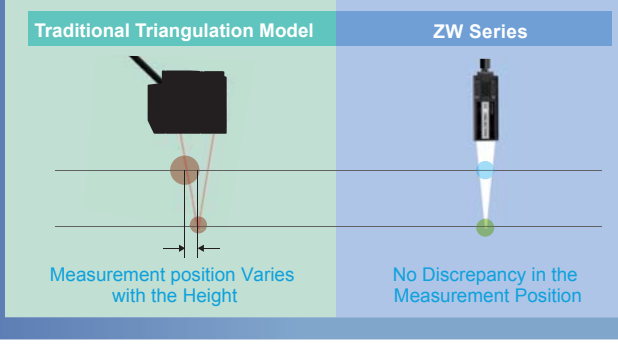
ZW-series Sensors operate on the confocal principle, so high-resolution measurements are possible regardless of inclination and warping of the measurement object.



(Sensor: ZW-S20)

No Discrepancy in the Measurement Point

Superior angle characteristics are not the only advantage of a confocal principle. With a traditional triangulation, the measurement position and spot size vary with the height. This means there are times when the position cannot be measured with high resolution due to warping and inclination. With the confocal principle used for the ZW Series, the measurement point remains the same at any position in the measuring range so that precise measurements can always be made.



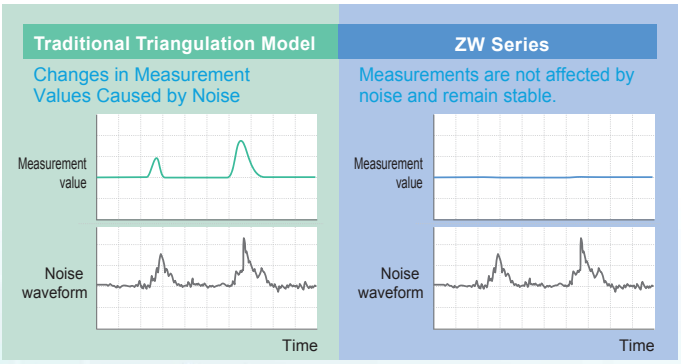
Robust Sensor Head Structure

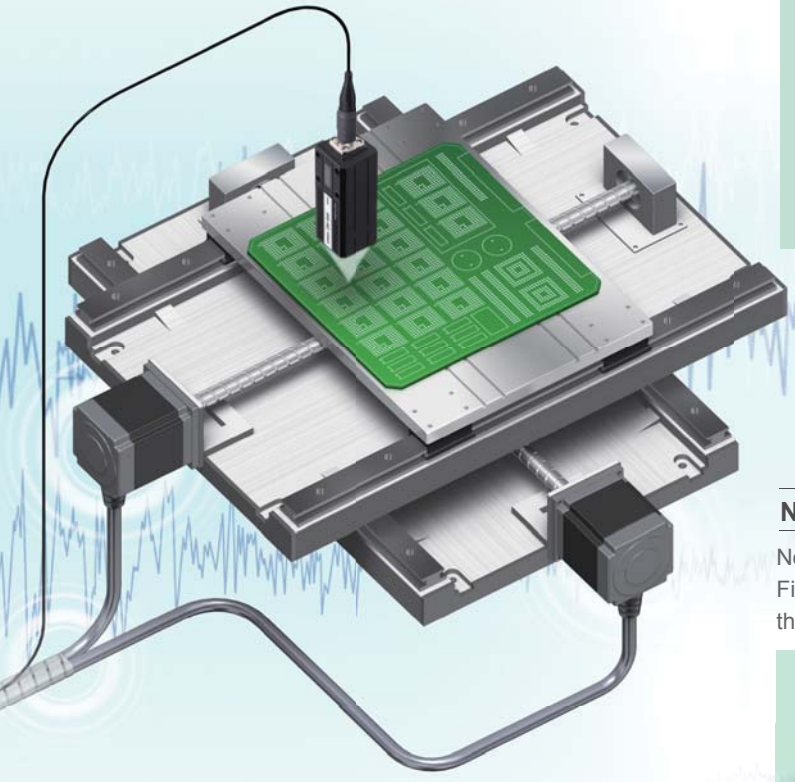
No Noise

Reduced Work for EMC Countermeasures

Not Affected by Noise

To ensure high-resolution measurements with normal sensors, countermeasures must be implemented to protect the sensor from the electromagnetic noise that is emitted by any nearby devices.The ZW-series Sensor Heads, however, contain no electronic parts to enable stable measurements even near power sections. Also, the Fiber Cable that connects the Sensor Head to the Controller can be placed near power lines and other cables that emit noise without affecting operation.

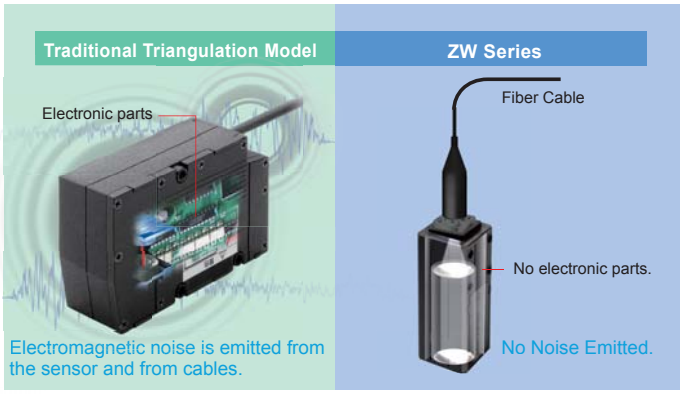




Substrate Height Inspection

No Noise Emission

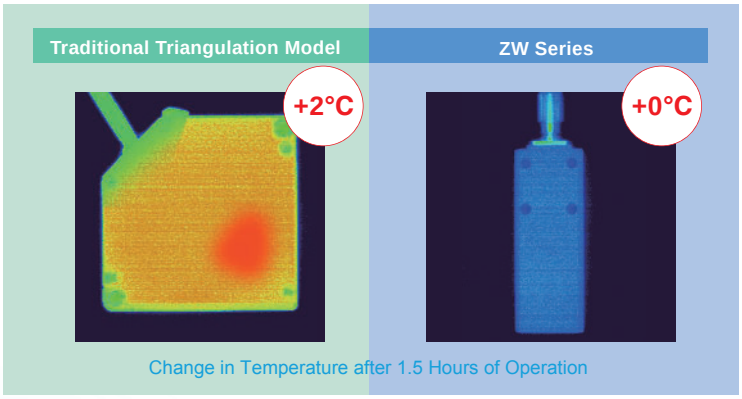
No electronic parts are used in the ZW -series Sensor Heads or Fiber Cables, so they give of f no electromagnetic noise. You can therefore use them reliably together with other devices.



No Heat Generation

Reduced Work in Thermal Design

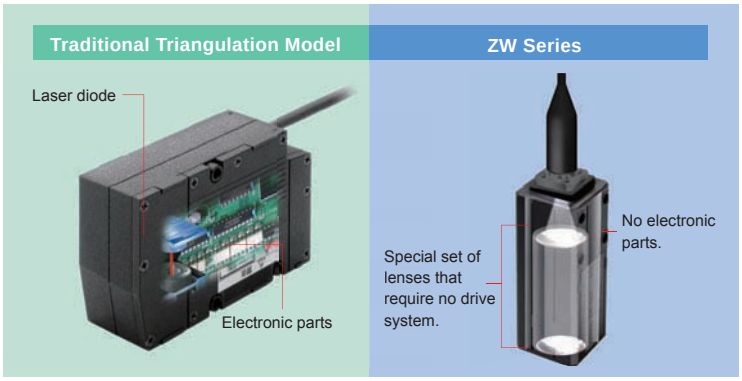
In high-resolution machine control, the heat generated by a sensor head can adversely af fect nearby equipment and cause the error to increase. The ZW-series Sensor Heads, however , generate no heat and therefore do not affect nearby equipment. You can also install many Sensor Heads side by side and still be sure of reliable operation.



No Electronic Parts

Reduced Maintenance Costs

Displacement sensors are often installed in moving applications and other installations that are subject to vibration. It is important that they can withstand this type of requirement. The ZW series Sensor Heads are designed for this type of environment, they have no electronic parts or PCB's that a standard triangulation sensor contains. The reduction of parts to lenses and fiber cables reduces the maintenance requirements, and the LED light source also eliminates the standard safety measures required for lasers.

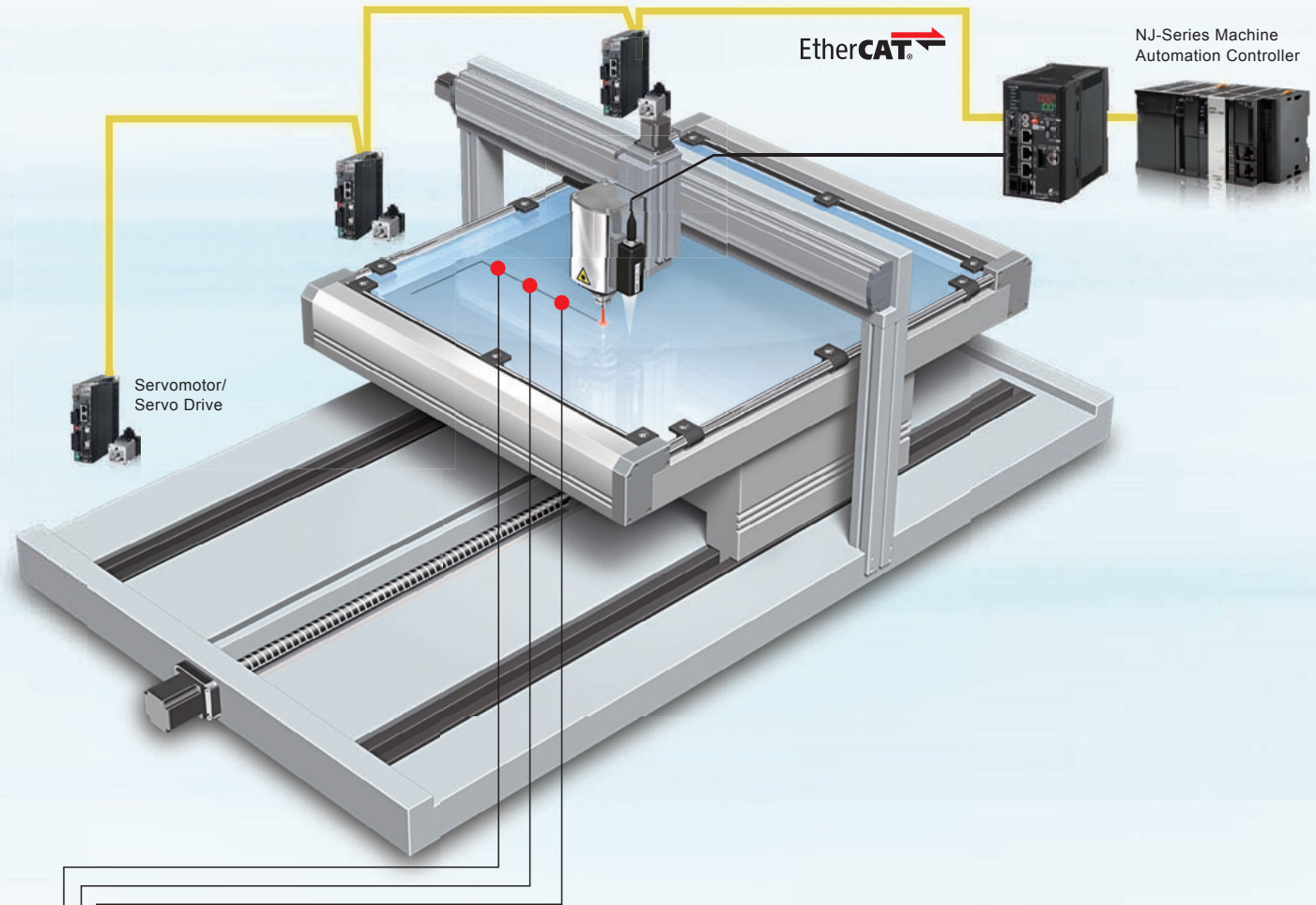


EtherCAT Machine Control Network

The EtherCAT high-speed open network was optimized for machine control. The ZW-series Sensors are the first OMRON Displacement Sensors with EtherCAT to provide a highly efficient design for high-precision machine control applications that use measurement results to control machine operation.

Combining Height Information and Position Coordinates

EtherCAT can be used to connect to servo drives or encoder input slaves to quickly get the position coordinates and ZW displace ment. The height information and XY position coordinates can be easily linked so that the machine control applications can increase processing precision in respect to the height and the inspection applications benefit from maintenance, such as helping to isolate errors or perform trend analysis.



Measurement point	Measurement result Z	Servo/encoder X	Servo/encoder Y
Point 1	Z1	X1	Y1
Point 2	Z2	X2	Y2
Point 3	Z3	X3	Y3
⋮	⋮	⋮	⋮

Results of Linking with the Position Coordinates

Machine Controls

- Increased processing precision
- No need for constant-speed control

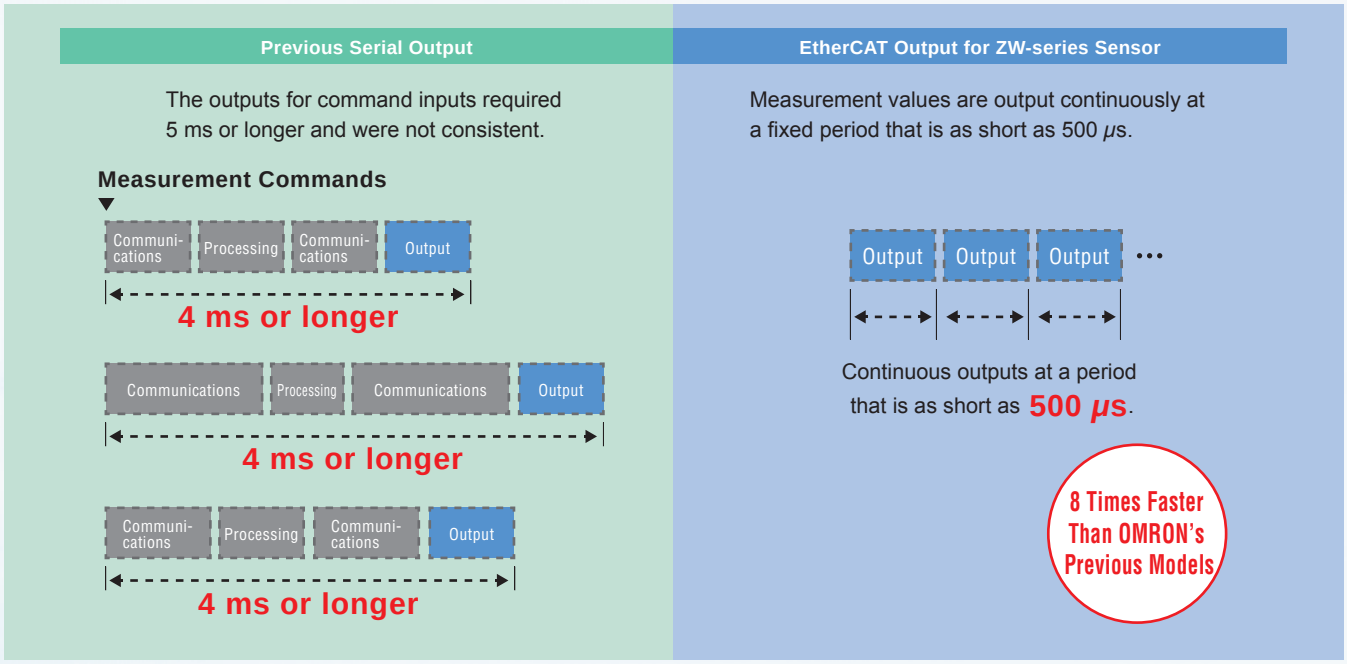
Inspection Applications

- Isolation of errors
- Trend management for specific positions

High-speed Digital Output

Shorter Machine Takt Times

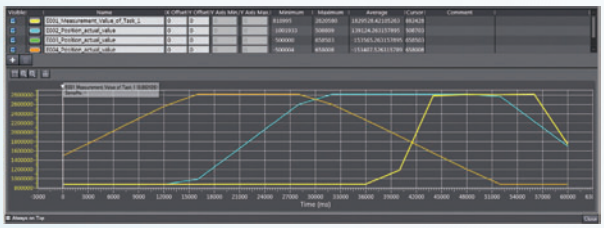
With previous digital (serial) outputs through Ethernet or RS-232C, the response period for measurement commands was both inconsistent and slow, making them unsuitable for realtime control. With EtherCAT, a constant period as short as 500 μs enables continuous digital (serial) outputs so that the overall workpiece height information can be mapped at high speed.



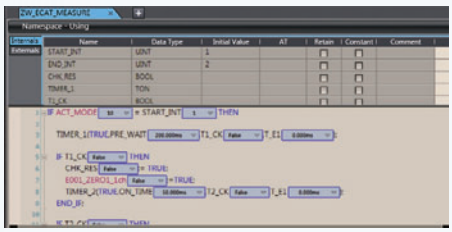
Tracing Machine Movement

Fewer Steps in System Commissioning

You can develop, test, and adjust devices that are connected via EtherCAT with just one Support Software package. The Automation Software Sysmac Studio allows you to creatively design your controls. You can see the entire range from sensing to motion control to reduce the number of steps required to commission the system or to aid in troubleshooting. There are also plenty of offline features to debug signal control programming. You can also simulate machine operation before actual application onsite.



Data Trace



Debugging Control Programming

Note: Sysmac Studio version 1.05 or higher is required for these software interface features described.

Long-distance Wiring: 100 m

Flexible Wiring for Machines

You can use EtherCAT to connect slaves that are up to 100 m apart. With digital communications, error does not occur due to the influences of ambient noise. This solves the previous problems with analog output methods, such as the inability to support long-distance transmissions and noise countermeasures, and enables reliable installation in previously difficult large-scale machines.

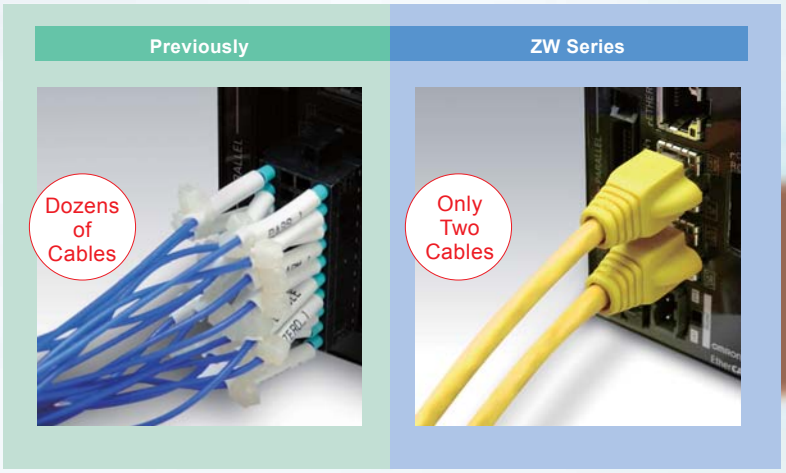
Multipoint Measurement with EtherCAT Concurrency

EtherCAT communications provide both high speed and time-consistent performance so that integrated controls for Sensors and other slaves can be achieved in realtime. Even for multipoint measurements for Displacement Sensor applications, the following advantages are provided.

Reduced Wiring: Only Two Cables

Less Wiring for Many Sensors

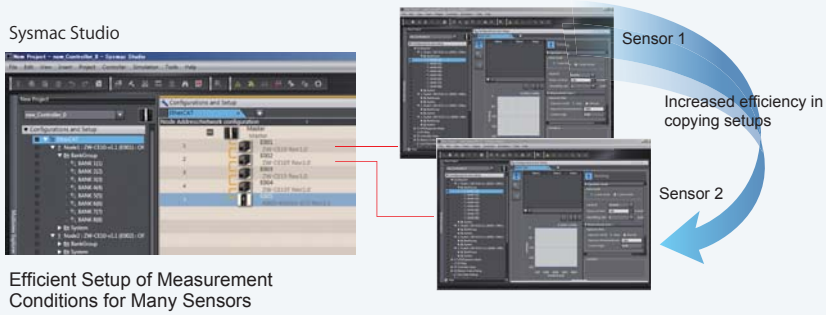
With previous parallel I/O, manual wiring was required for dozens of points, and it was necessary to take sufficient caution to avoid sources of noise. This required extensive time to use many Displacement Sensors in a row . With EtherCAT, all you have to do is connect two lines for each Controller.



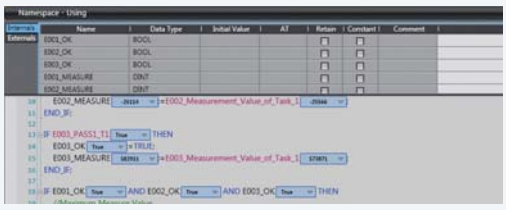
One Software

Fewer Steps in System Design

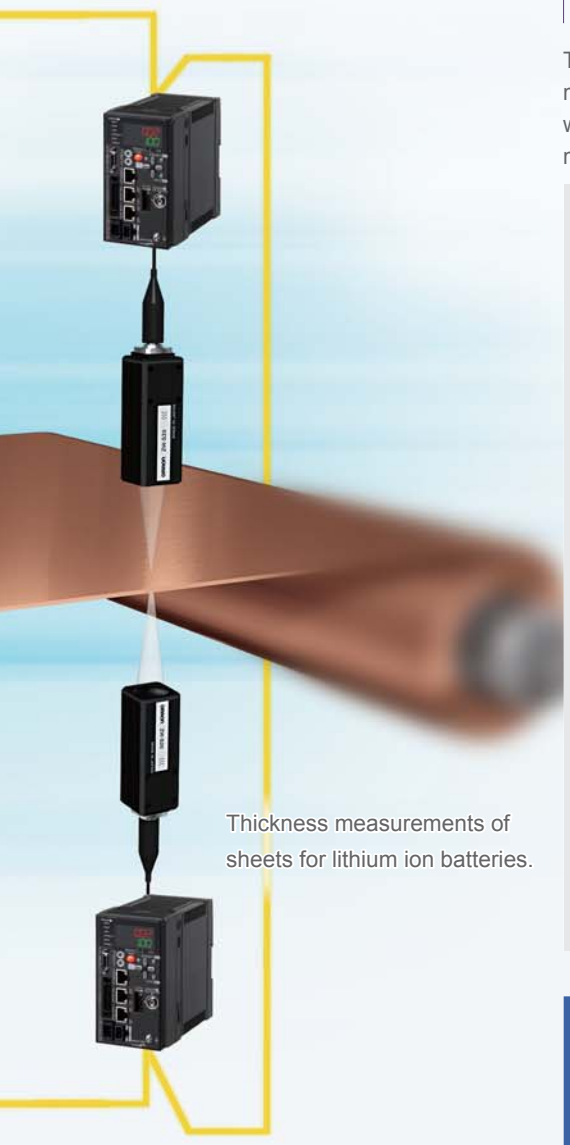
You can set up all of the slaves that are connected via EtherCAT with just the Automation Software Sysmac Studio. Even when you combine many Sensors, you can copy setup data to effectively integrate setup work or you can easily program calculations between the Sensors.



Efficient Setup of Measurement Conditions for Many Sensors



Easy Programming of Thickness Calculations

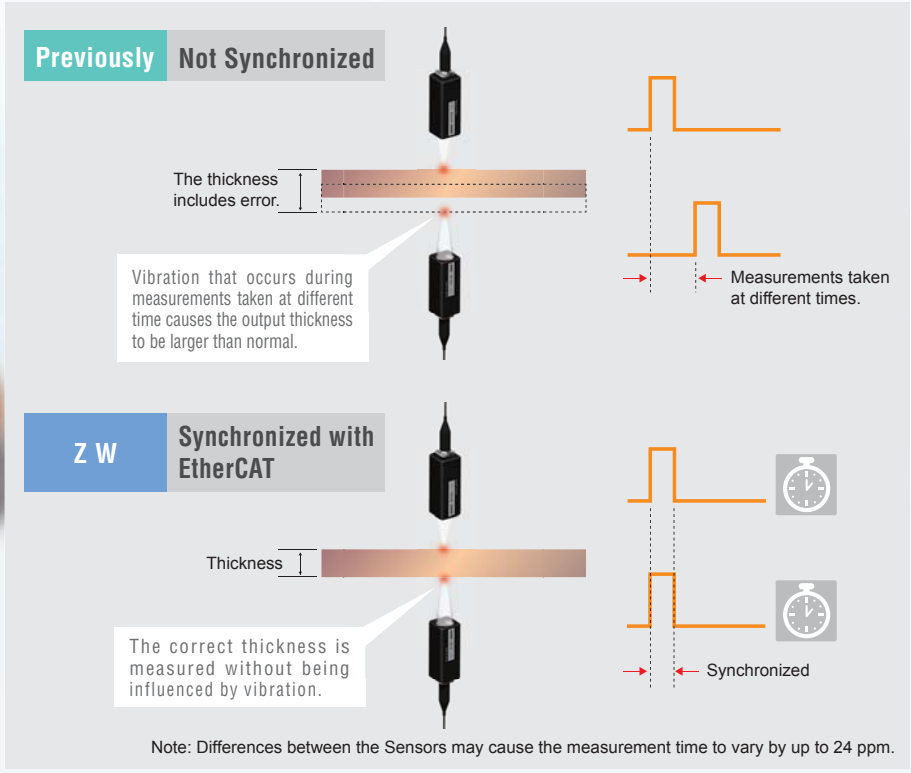


Thickness measurements of sheets for lithium ion batteries.

Synchronous Measurements

Fewer Thickness Errors due to Vibration

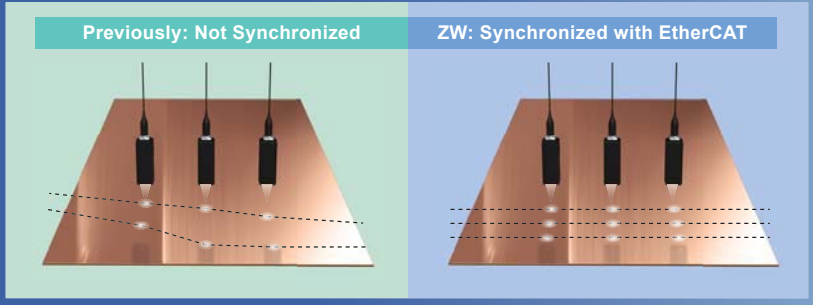
The highly precise synchronization performance of EtherCA T reduces the time error in measurements between different Sensors to 1 μs or less. Synchronous measurement is useful when measurements must be made with more than one Sensor at the same time, such as measurements from both sides of a sheet or inclination control of a substrate.



Note: Differences between the Sensors may cause the measurement time to vary by up to 24 ppm.

Continuous Measurements of Sheets without Position Offset

When Sensors are installed in a row to continuously log sheet height, nonsynchronous measurements can cause of fsets in the lateral measurement positions. With synchronous measurements using EtherCAT, you can continuously log sheet height with all of the Sensors at the same lateral position.



Robust Sensor Head Structure

To achieve a compact Sensor Head and high-resolution measurements, the ZW Series uses a white light confocal principle to detect objects. This principle is described below.

OCFL Module

The OCFL module contains a special lens set developed by OMRON that changes the focal point for each color (i.e., wavelength) of white light.The spot diameter is the same at any position within the measuring range. It does not change the way it does for a triangulation. High-precision lens manufacturing technology has allowed us to achieve a lens structure that is extremely small and that also does not require a drive mechanism.

OCFL

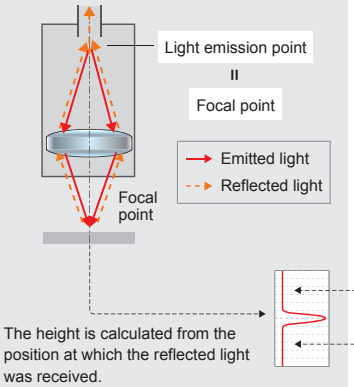
*OCFL : Omron Chromatic Focus Lens

Confocal principle Confocal Light Emission and Reception

Based on the confocal principle, the emitted light and received light are positioned along the same axis. Light is received only when it is focused on the measurement object, allowing the height to be calculated. Unlike triangulation, the received light waveform is not disrupted by the material or inclination of the measurement object. The received light waveform is always stable, which enables high-resolution measurements.

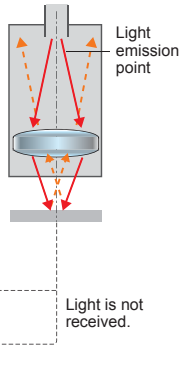
Object Located at Focal Point

The reflected light is focused at the same point as the emitted light.The reflected light becomes the received light signal.



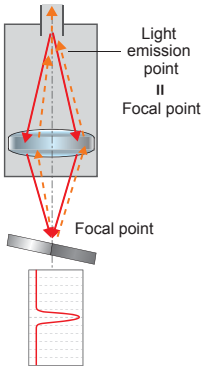
Object Not Located at Focal Point

Reflected light is not received because the reflected light is not focused at the light emission point.



Inclination and Differences in Materials

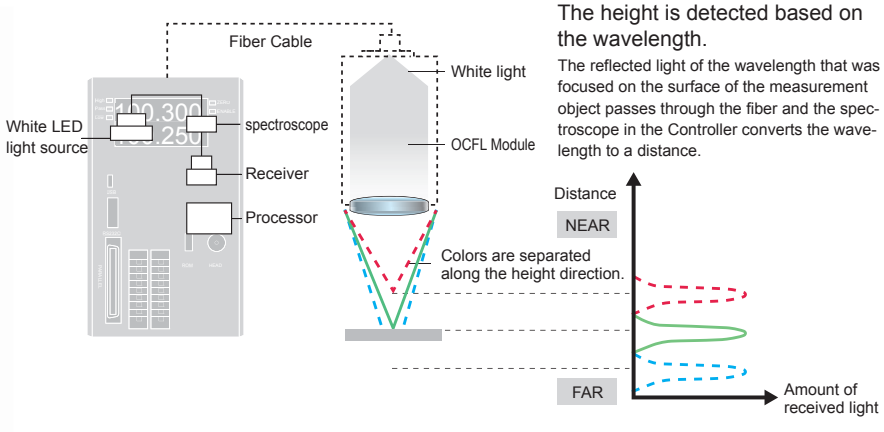
Even if the measurement object is inclined or contains dif ferent materials, the reflected light will be focused at the light emission point as long as the measurement object is at the focal point.



White White Light Separation into Colors with Different Wavelengths at Emission

Patent Pending

The white light from the LED is focused at different points for each color (i.e., wavelength) due to a special set of lenses in the OCFL module in the Sensor Head. As a result, only the color of light that is focused on the measurement object is returned, allowing the distance from the Sensor Head to the measurement object to be calculated based on the color of the reflected light. The Sensor Head contains the special set of lenses that separates white light into dif ferent colors and the Controller contains the white LED light source, and the spectroscope and processor that convert the color of the reflected light to a distanceThere is no needs for a lens drive mechanism or electronic parts in the Sensor Head, even though they were considered to be standard in previous confocal models. This achieves a much more compact design and much greater immunity to noise than triangulation models and or previous confocal models.

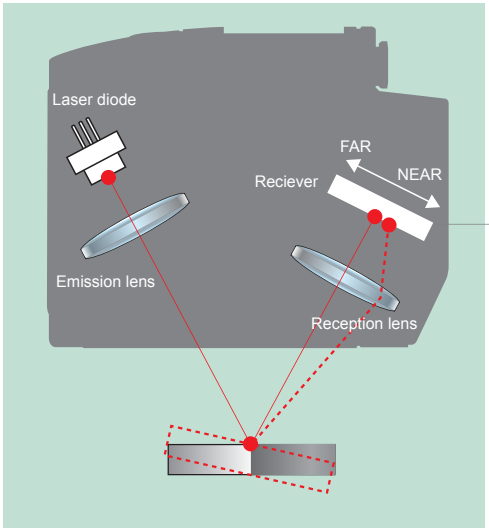


The height is detected based on the wavelength.

The reflected light of the wavelength that was focused on the surface of the measurement object passes through the fiber and the spectroscope in the Controller converts the wavelength to a distance.

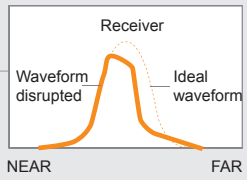
Problems with Previous Models

Triangulation



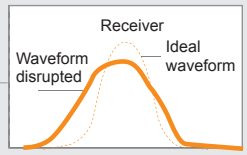
Triangulation measures the height of an object based on the position of the spot on a receiver (CCD or CMOS). The peak, center of gravity, and other features are calculated from the received light waveform to reduce error , but in principle, the received waveform is offset or disrupted due to differences in materials or inclination. This results in measurement error.

Light Reception for Different Materials



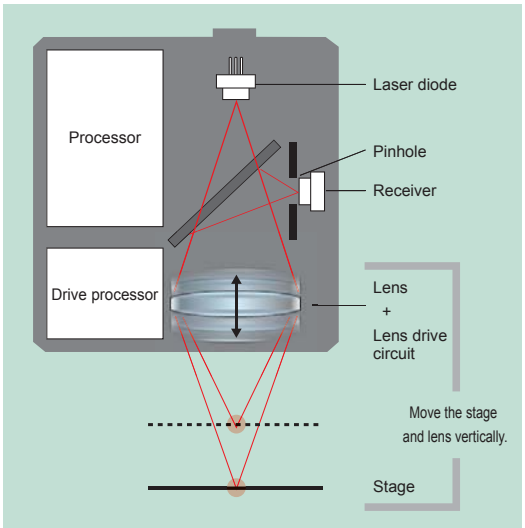
Different materials have dif ferent reflection factors. This disrupts the waveform that is received on the receiver.The peak in the waveform or the center of gravity are used to calculate the height, but error will remain in the measurement results.

Light Reception for Inclination



If the measurement object is inclined, the received waveform is offset or disrupted due to the effects of aberration. This results in measurement error.

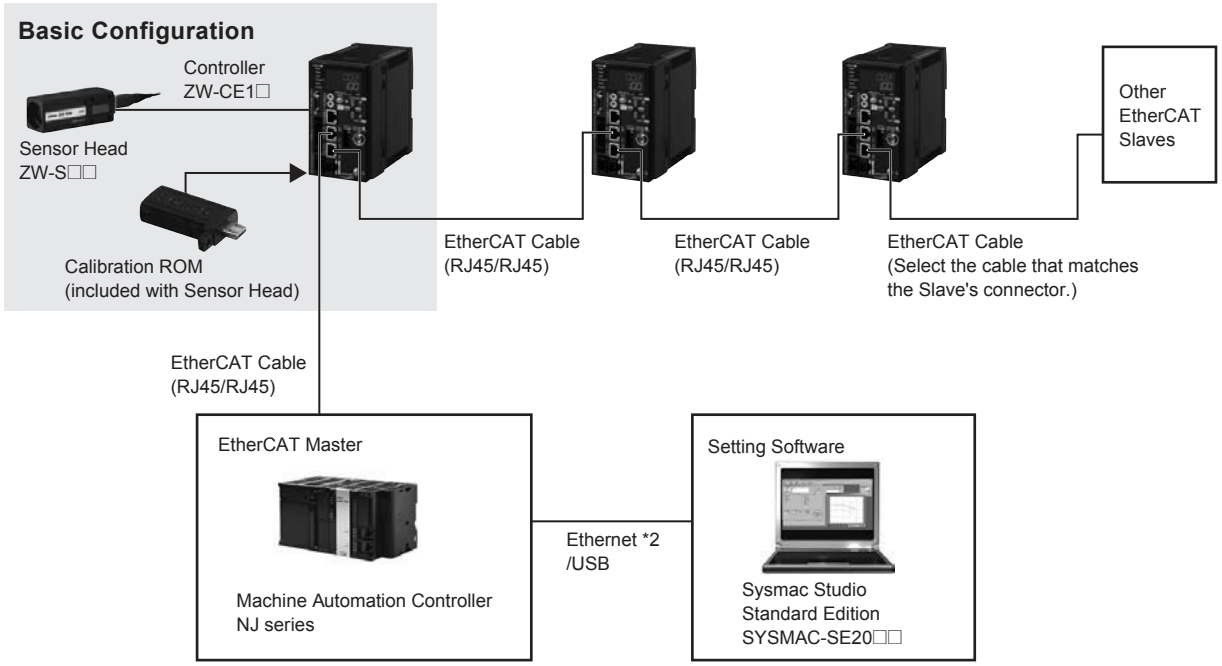
Normal Confocal Principle



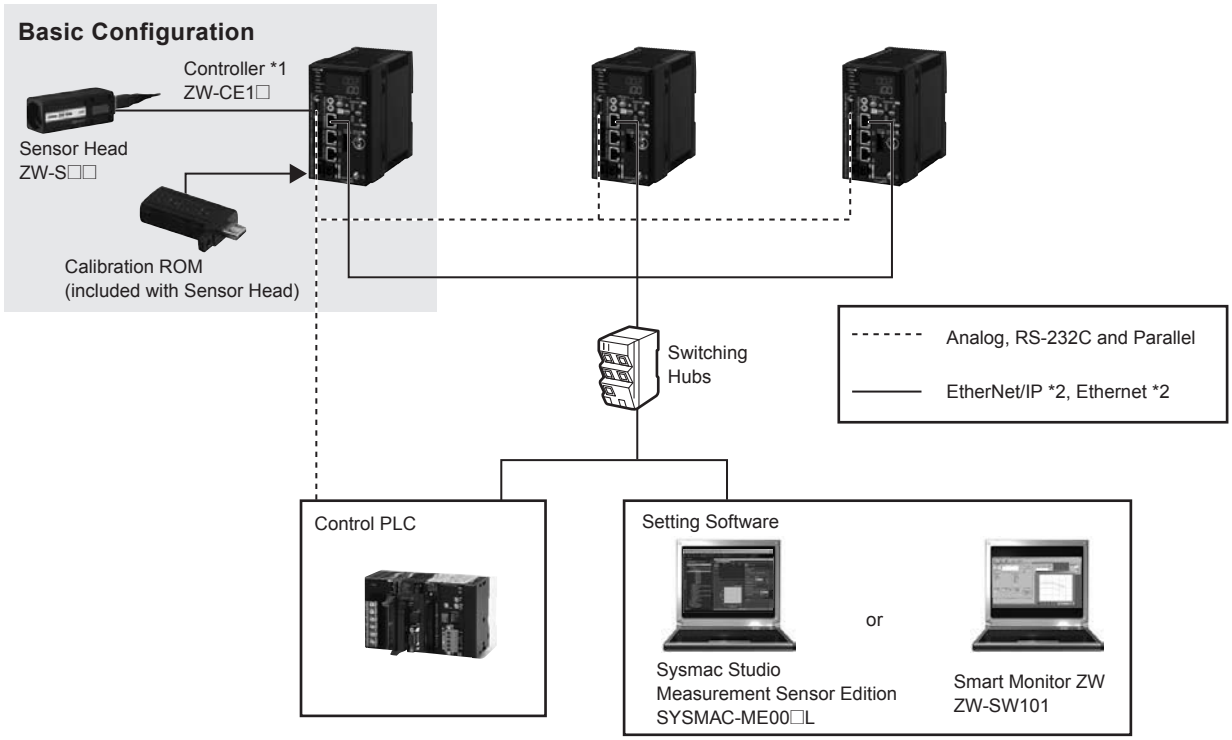
In a normal confocal model, a stage and lens are driven vertically to change the focal point. This requires a more complex structure, and the large number of parts interferes with downsizing. The use of a laser beam increases the chances of interference, and the received light waveform can be disrupted by the surface conditions within the small spot on the measurement object.

System Configuration

EtherCAT connections



Analog, EtherNet/IP, Ethernet, RS-232C and Parallel connections

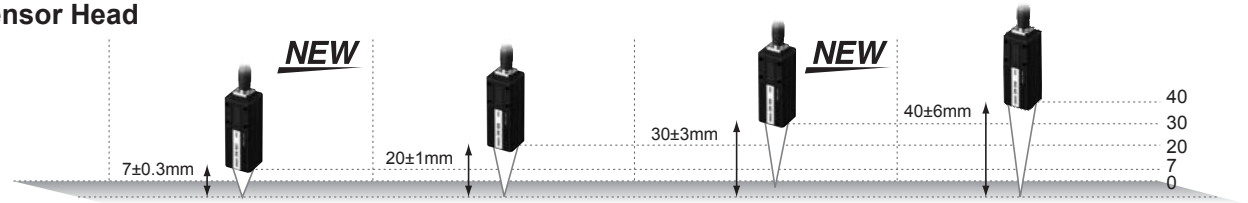


✻1 Controllers with binary outputs are also available (ZW-C10T/-C15T).
Please contact your OMRON sales representative for details.

✻2 Prepare commercially available Ethernet cable satisfying the following requirements:
- Category 5e or more, 30 m or less
- RJ45 connector (8-pin modular jack)
- For direct connection: Select cross cable.
- For connection through an industrial switching hub: Select straight cable.

Order Information

● Sensor Head



Measuring range	7±0.3mm	20±1mm	30±3mm	40±6mm
Spot diameter	18 μm dia.	40 μm dia.	60 μm dia.	80 μm dia.
Static resolution	*0.01μm / 0.25μm	*0.02μm / 0.25μm	*0.06μm / 0.25μm	*0.08μm / 0.25μm
Model	**ZW-S07**	**ZW-S20**	**ZW-S30**	**ZW-S40**

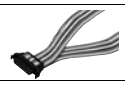
Note: When ordering, specify the cable length (0.3 m, 2.0 m). * The high resolution types are subject to the export control restrictions

●Controller with EtherCAT

Appearance	Power supply	Output type	Model
	DC24V	NPN	**ZW-CE10T / *ZW-CE10**
		PNP	**ZW-CE15T / *ZW-CE15**

Note: Controllers with binary outputs are also available (ZW-C10T/-C15T). * The high resolution types are subject to the export control restrictions

●Cable

Appearance	Item	Cable length	Model
	Sensor Head - Controller Extension Fiber Cable (flexible cable) (Fiber Adapter ZW-XFC provided)	2m	**ZW-XF02R**
		5m	**ZW-XF05R**
		10m	**ZW-XF10R**
		20m	**ZW-XF20R**
		30m	**ZW-XF30R**
	Fiber Adapter (between Sensor Head pre-wired cable and Extension Fiber Cable)	—	**ZW-XFC**
	Parallel cable for ZW-CE1□T 32-pole* (included with Controller ZW-CE1□T)	2m	**ZW-XCP2E**
	RS-232C Cable for personal computer	2m	**ZW-XRS2**
	RS-232C Cable for PLC/programmable terminal	2m	**ZW-XPT2**

✻ A parallel cable for Controllers with binary outputs is also available (ZW-XCP2). Please contact your OMRON sales representative for details.

●Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually.
Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model	Standards
Sysmac Studio Standard Edition Ver.1.□□ *2	The Sysmac Studio provides an integrated development environment to set up, program, debug, and maintain NJ-series Controllers and other Machine Automation Controllers, as well as EtherCAT slaves.	— (Media only)	DVD	**SYSMAC-SE200D**	—
	Sysmac Studio runs on the following OS. Windows XP (Service Pack 3 or higher, 32-bit version)/Vista(32-bit version)/7(32-bit/64-bit version) This software provides functions of the Measurement Sensor Edition. Refer to Sysmac Catalog (P072) for details such as supported models and functions.	1 license*1	—	**SYSMAC-SE201L**	—
Sysmac Studio Measurement Sensor Edition Ver.1.□□ *3	Sysmac Studio Measurement Sensor Edition is a limited license that provides selected functions required for ZW-series Displacement Sensor settings. Because this product is a license only, you need the Sysmac Standard Edition DVD media to install it.	1 license	—	**SYSMAC-ME001L**	—
		3 license	—	**SYSMAC-ME003L**	—

✻1. Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).
✻2. ZW-series is supported by Sysmac Studio version 1.05 or higher.
✻3. Setting Software Smart Monitor ZW is also available (ZW-SW101). Please contact your OMRON representative for details.

●Accessories

Item	Model
Fiber Connector Cleaner	**ZW-XCL**

Note: Place orders in units of boxes (contacting 10 units).

●Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

●Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length(m) *1	Model
Standard type Cable with Connectors on Both Ends (RJ45/RJ45) Wire Gauge and Number of Pairs: AWG27, 4-pair Cable Cable Sheath material: LSZH *2 Cable color: Yellow *3		OMRON	0.3	**XS6W-6LSZH8SS30CM-Y**
			0.5	**XS6W-6LSZH8SS50CM-Y**
			1	**XS6W-6LSZH8SS100CM-Y**
			2	**XS6W-6LSZH8SS200CM-Y**
			3	**XS6W-6LSZH8SS300CM-Y**
			5	**XS6W-6LSZH8SS500CM-Y**
Rugged type Cable with Connectors on Both Ends (RJ45/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	**XS5W-T421-AMD-K**
			0.5	**XS5W-T421-BMD-K**
			1	**XS5W-T421-CMD-K**
			2	**XS5W-T421-DMD-K**
			5	**XS5W-T421-GMD-K**
			10	**XS5W-T421-JMD-K**
Rugged type Cable with Connectors on Both Ends (M12 Straight/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	**XS5W-T421-AMC-K**
			0.5	**XS5W-T421-BMC-K**
			1	**XS5W-T421-CMC-K**
			2	**XS5W-T421-DMC-K**
			5	**XS5W-T421-GMC-K**
			10	**XS5W-T421-JMC-K**
Rugged type Cable with Connectors on Both Ends (M12 Right-angle/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	**XS5W-T422-AMC-K**
			0.5	**XS5W-T422-BMC-K**
			1	**XS5W-T422-CMC-K**
			2	**XS5W-T422-DMC-K**
			5	**XS5W-T422-GMC-K**
			10	**XS5W-T422-JMC-K**

Note: For details, refer to Cat.No.G019.
***1.** Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20m are available.
Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15m are available.
***2.** The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use.
***3.** Cables colors are available in blue, yellow, or Green

●Cables / Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	—	Hitachi Cable, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *
	—	Kuramo Electric Co.	KETH-SB *
	—	SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors	—	Panduit Corporation	MPS588-C *

✻ We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	—	Kuramo Electric Co.	KETH-PSB-OMR *
	—	Nihon Electric Wire&Cable Co.,Ltd.	PNET/B *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

Note: Connect both ends of cable shielded wires to the connector hoods.
✻ We recommend you to use above cable and connector together.

●Industrial switching hubs for Ethernet

Appearance	Number of ports	Failure detection	Current consumption	Model
	3	None	0.22A	**W4S1-03B**
	5	None	0.22A	**W4S1-05B**
		Supported		**W4S1-05C**

Note: Industrial switching hubs are cannot be used for EtherCAT.

●EtherCAT junction slaves

Appearance	Number of ports	Power supply voltage	Current consumption	Model
	3	20.4 to 28.8 VDC (24 VDC -15 to 20%)	0.08A	**GX-JC03**
	6		0.17A	**GX-JC06**

Note: **1.** Please do not connect EtherCAT junction slave with OMRON position control unit, Model CJ1W-NC□81/□82.
2. EtherCAT junction slaves cannot be used for EtherNet/IP™ and Ethernet.

Specifications

●Sensor Head

Item		ZW-S07	ZW-S20	ZW-S30	ZW-S40
Measuring center distance		7mm	20 mm	30mm	40 mm
Measuring range		±0.3mm	±1 mm	±3mm	±6 mm
Static resolution *1		0.25 μm	0.25 μm	0.25 μm	0.25 μm
Linearity *2		±0.8 μm	±1.2 μm	±4.5 μm	±7.0 μm
Spot diameter *3	Near	20 μm dia.	45 μm dia.	70 μm dia.	90 μm dia.
	Center	18 μm dia.	40 μm dia.	60 μm dia.	80 μm dia
	Far	20 μm dia.	45 μm dia.	70 μm dia.	90 μm dia
Measuring cycle		500 μs to 10 ms			
Operating ambient illumination		Illumination on object surface 10,000 lx or less: incandescent light			
Ambient temperature range		Operating: 0 to 50°C, Storage: −15 to 60°C (with no icing or condensation)			
Ambient humidity range		Operating and storage: 35% to 85% (with no condensation)			
Degree of protection		IP40 (IEC60529)			
Vibration resistance (destructive)		10 to 150 Hz, 0.35 mm single amplitude, 80 min each in X, Y, and Z directions			
Shock resistance (destructive)		150 m/s^2 3 times each in six directions (up/down, left/right, forward/backward)			
Temperature characteristic *4		0.6 μm/ °C	1.5 μm/ °C	2.8 μm/ °C	4.8 μm/ °C
Materials		Case: aluminum die-cast Fiber cable sheat: PVC Calibration ROM: PC			
Fiber cable length		0.3 m, 2 m (Flex-resistant cable)			
Fiber cable minimum bending radius		20 mm			
Insulation resistance (Calibration ROM)		Between case and all terminals: 20 MΩ (by 250 V megger)			
Dielectric strength (Calibration ROM)		Between case and all terminals: 1,000 VAC, 50/60 Hz, 1 min			
Weight		Approx. 105 g (Chassis, fiber cable total)			
Accessories included with sensor head		Instruction sheet, Fixing screw (M2) for Calibration ROM, Precautions for correct use			

✻1. Capacity value when Omron standard mirror surface target is measured at the measurement center distance as the average of 4,096 times.
✻2. Material setting for the Omron standard mirror surface target: Error from an ideal straight line when measuring on mirror surface.
The reference values for linearity when targets to measure other than the above are as in the table below.

Item	ZW-S07	ZW-S20	ZW-S30	ZW-S40
Grass	±1.0 μm	±1.2 μm	±4.5 μm	±7.0 μm
SUS BA	±1.2 μm	±1.4 μm	±5.5 μm	±8.5 μm
White ceramic	±1.6 μm	±1.7 μm	±6.4 μm	±9.5 μm

✻3. Capacity value defined by 1/e^2 (13.5%) of the center optical intensity in the measured area.
✻4. Temperature characteristic at the measurement center distance when fastened with an aluminum jig between the Sensor Head and the target and the Sensor Head and the controller are set in the same temperature environment.

●Automation Software Sysmac Studio

System Requirements

Item	Requirement
Operating system (OS) *1 *2	Windows XP (Service Pack 3 or higher, 32-bit version)/Vista(32-bit version)/7(32-bit/64-bit version)
CPU	Windows computers with Celeron 540 (1.8 GHz) or faster CPU. Core i5 M520 (2.4 GHz) or equivalent or faster recommended
Main memory	2 GB min.
Recommended videomemory / video card for using 3D motion trace	Video memory: 512 MB min. Video card: Either of the following video cards: • NVIDIAR GeForceR 200 Series or higher • ATI RadeonHD5000 Series or higher
Hard disk	At least 1.6 GB of available space
Display	XGA 1024 × 768, 16 million colors. WXGA 1280 × 800 min. recommended
Disk drive	DVD-ROM drive
Communications ports	USB port corresponded to USB 2.0, or Ethernet port *3
Supported languages	Japanese, English, German, French, Italian, Spanish, simplified Chinese, traditional Chinese, Korean

✻1. Sysmac Studio Operating System Precaution: System requirements and hard disk space may vary with the system environment.
✻2. The following restrictions apply when Sysmac Studio is used with Microsoft Windows Vista or Windows 7.
Some Help files cannot be accessed.
The Help files can be accessed if the Help program distributed by Microsoft for Windows (WinHlp32.exe) is installed. Refer to the Microsoft homepage listed below or contact Microsoft for details on installing the file. (The download page is automatically displayed if the Help files are opened while the user is connected to the Internet.)
http://support.microsoft.com/kb/917607/en-us
✻3. Refer to the hardware manual for your Controller for hardware connection methods and cables to connect the computer and Controller.

●Setting Software Smart Monitor ZW ZW-SW101

System Requirements

Item	Condition
Operating System(OS)	Windows 7 (32 or 64-bit version) Windows XP (Service Pack3 or more, 32-bit version)
CPU	Intel Pentium III, 850 MHz or more (2 GHz or more is recommended.)
Main memory	1 GB or more
Hard disk	50 MB or more
Display	1024 × 768 dots or more, 16 million colors or more
Supported languages	Japanese/English
Communication port	Ethernet port

●Controller

Item				ZW-CE10T	ZW-CE15T
Input/Output type				NPN	PNP
Number of connected Sensor Heads				1 per Controller	
Sensor Head compatibility				Available	
Light source for measurement				White LED	
Segment display	Main display			11-segment red display, 6 digits	
	Sub-display			11-segment green display, 6 digits	
LED display	Status indicators			HIGH (orange), PASS (green), LOW (orange), STABILITY (green), ZERO (green), ENABLE (green), THRESHOLD-H (orange), THRESHOLD-L (orange), RUN (green)	
	EtherCAT indicators			L/A IN(Link Activity IN)(green), L/O OUT(Link Activity OUT)(green), ECAT RUN(green), ECAT ERR(red)	
External interface	Ethernet			100BASE-TX, 10BASE-T, No-protocol Communications (TCP/UDP), EtherNet/IP™	
	EtherCAT			EtherCAT-specific protocol 100BASE-TX	
	RS-232C			115,200 bps max.	
	Analog output terminal block	Analog voltage output (OUT1V)		-10 V to +10 V, output impedance: 100 Ω	
		Analog current output (OUT1A)		4 mA to 20 mA, maximum load resistance: 300Ω	
	32-pole extension connector	Judgment output (HIGH1/PASS1/LOW1)		Transistor output system Output voltage: 21.6 to 30 VDC Load current: 50 mA or less Residual voltage when turning ON: 1.2 V or less Leakage voltage when turning OFF: 0.1 mA or les	
		BUSY output (BUSY1)			
		ALARM output (ALARM1)			
		ENABLE output (ENABLE)			
		LED OFF input (LED OFF1)		DC input system Input voltage: 24 VDC ±10% (21.6 to 26.4 VDC) Input current: 7 mA Typ. (24 VDC) Voltage/Current when turning ON: 19 V/3 mA or more Voltage/Current when turning OFF:5 V/1 mA or less	
		ZERO RESET input (ZERO)			
		TIMING output (TIMING1)			
		RESET output (RESET1)			
		Bank	Selected bank output (BANK_OUT 1 to 3)	Transistor output system Output voltage: 21.6 to 30 VDC Load current: 50 mA or less Residual voltage when turning ON: 1.2 V or less Leakage voltage when turning OFF: 0.1 mA or less	
			Selected bank input (BANK_SEL 1 to 3)	DC input system Input voltage: 21.6 to 26 VDC Input current: 7 mA Typ. (24 VDC) Voltage/Current when turning ON: 19 V/3 mA or more Voltage/Current when turning OFF:5 V/1 mA or less	
Main functions	Exposure time			Auto/Manual	
	Measuring cycle			500 μs to 10 ms	
	Material setting			Standard/Mirror/Diffusion surfaces	
	Measurement Item			Height/Thickness/Calculation	
	Filtering			Median/Average/Differentiation/High pass/Low pass/Band pass	
	Outputs			Scaling/Different holds/Zero reset/Logging for a measured value	
	Display			Measured value/Threshold value/Analog output voltage or current value/Judgment result/ Resolution/Exposure time	
	Number of configurable banks			Max. 8 banks	
	Task process			Multi-task (up to 4 tasks per bank)	
	System			Save/Initialization/Display measurement information/Communication settings/Sensor Head calibration/Key-lock/Trigger-key input	
Ratings	Power supply voltage			21.6 to 26.4 VDC (including ripple)	
	Current consumption			600 mA max.	
	Insulation resistance			Across all lead wires and controller case: 20 MΩ(by 250 V megger)	
	Dialectic strength			Across all lead wires and controller case: 1,000 VAC, 50/60 Hz, 1 min.	
Environmental	Degree of protection			IP20(IEC60529)	
	Vibration resistance (destructive)			10 to 55 Hz, 0.35-mm single amplitude, 50 min each in X, Y, and Z directions	
	Shock resistance (destructive)			150 m/s^2, 3 times each in six directions (up/down, left/right, forward/backward)	
	Ambient temperature			Operating: 0 to 40°C Storage:-15 to 60°C (with no icing or condensation)	
	Ambient humidity			Operating and storage: 35% to 85% (with no condensation)	
Grounding				D-type grounding (Grounding resistance of 100 Ω or less) Note: For conventional Class D grounding	
Materials				Case: PC	
Weight				Approx. 750 g (main unit only), Approx. 150 g (Parallel Cable)	
Accessories included with controller				Instruction sheet,Member registration sheet, Parallel cable ZW-XCP2E	

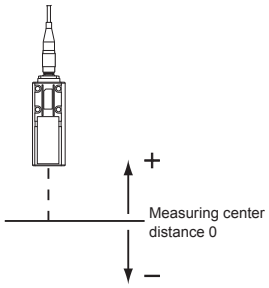
Note: Controllers with binary outputs are also available (ZW-C10T/-C15T). Please contact your OMRON sales representative for details.

●ZW Series EtherCAT Communications Specifications

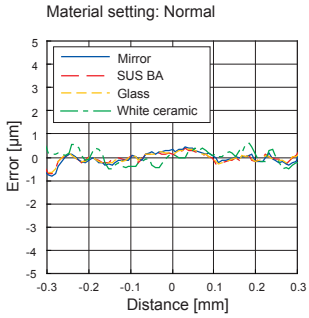
Item	Specification
Communications standard	IEC61158 Type12
Physical layer	100BASE-TX(IEEE802.3)
Connectors	RJ45 × 2 ECAT IN: EtherCAT input ECAT OUT: EtherCAT output
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.
Communications distance	Distance between nodes: 100 m max.
Process data	Variable PDO mapping
Mailbox (CoE)	Emergency messages, SDO requests, SDO responses, and SDO information
Distributed clock	Synchronization in DC mode.
LED display	L/A IN (Link/Activity IN) × 1, AL/A OUT (Link/Activity OUT) × 1, AECAT RUN × 1, AECAT ERR × 1

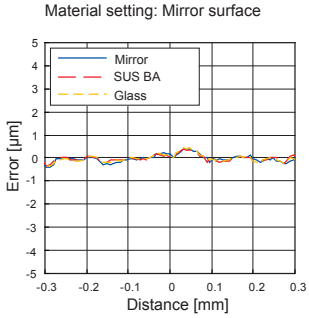
Characteristic data (typical examples)

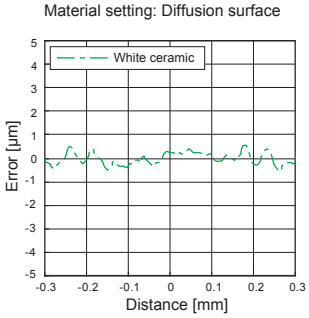
Linearity Characteristic by Materials



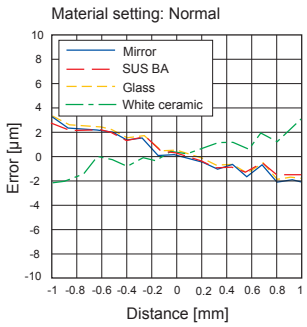
ZW-S07

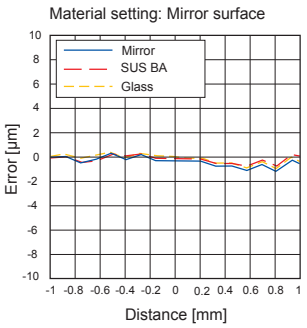


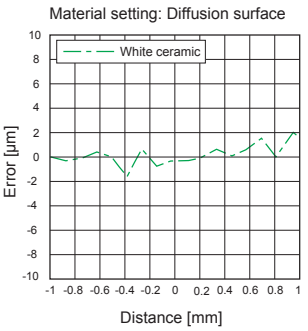




ZW-S20







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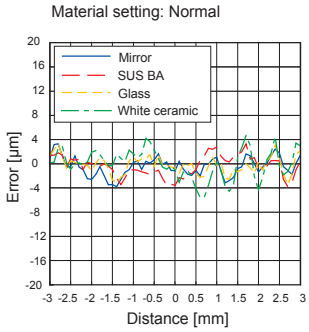

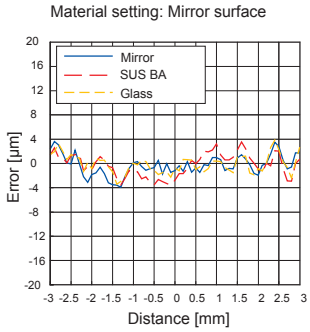

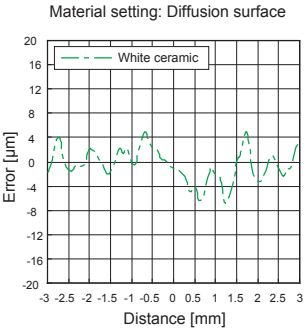

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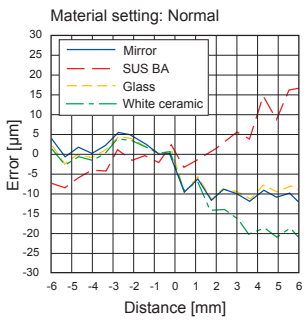
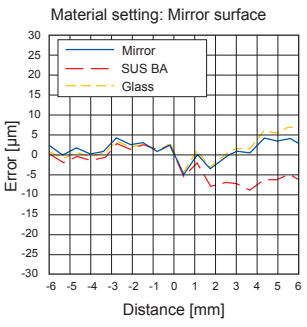
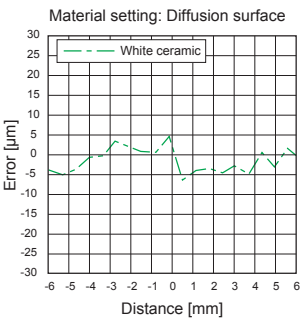
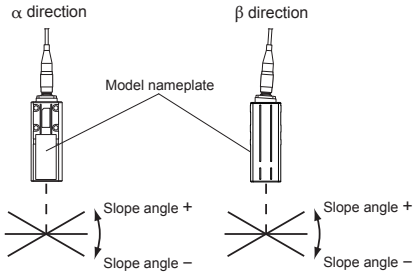




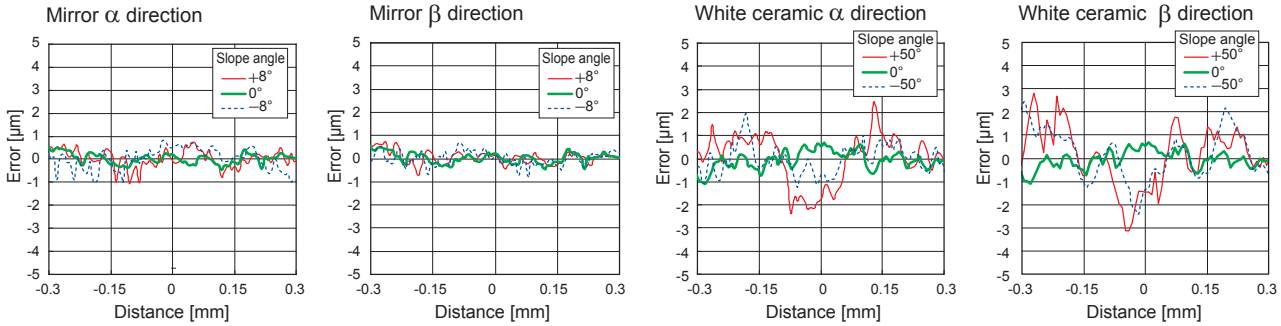


●Angle Characteristic *



✻ The above show the results after executing scaling.

ZW-S07



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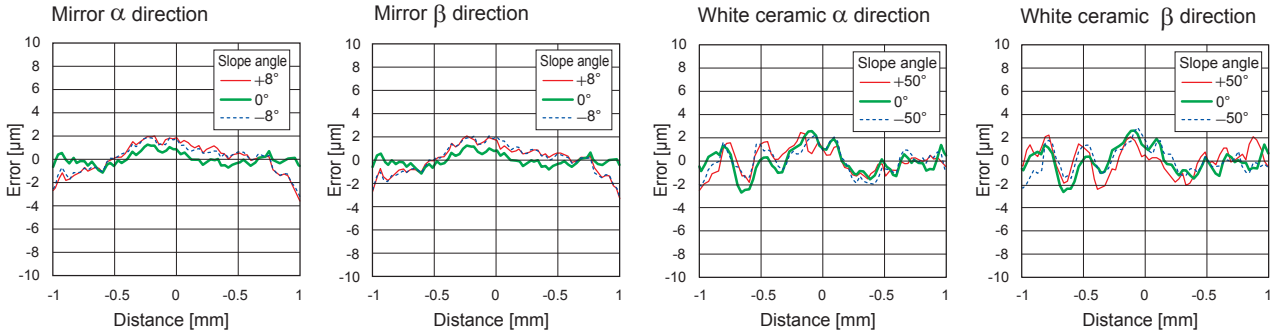
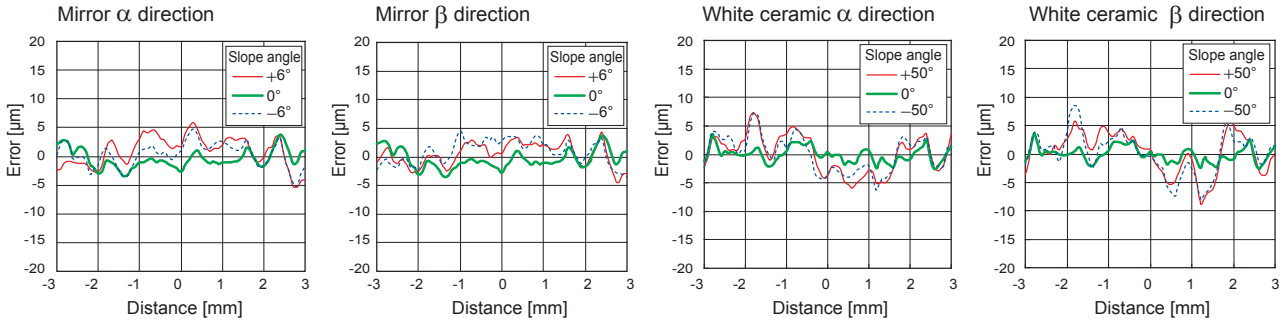


ZW-S30



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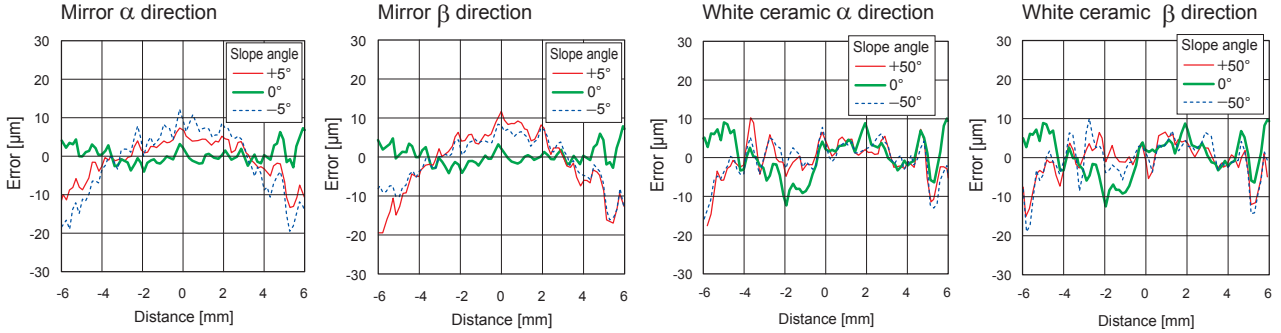
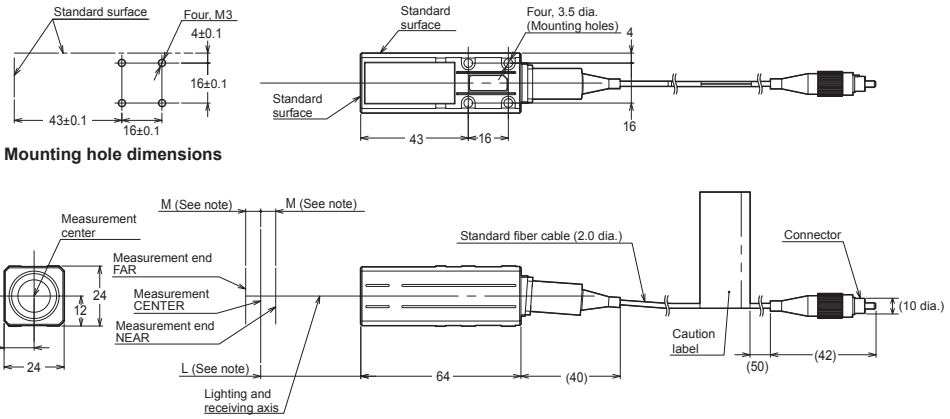


External Dimensions

(Unit: mm)

Sensor Head

ZW-S07/-S20/-S30/-S40

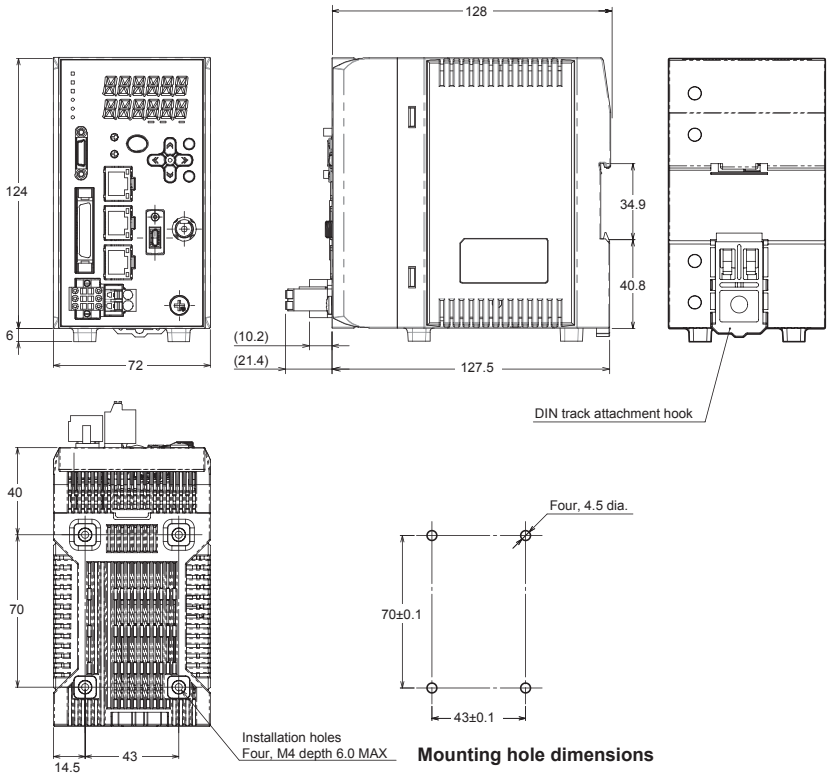


Note:

Model	L	M	X
ZW-S07	7	0.3	12
ZW-S20	20	1	11.8
ZW-S30	30	3	11.7
ZW-S40	40	6	11.7

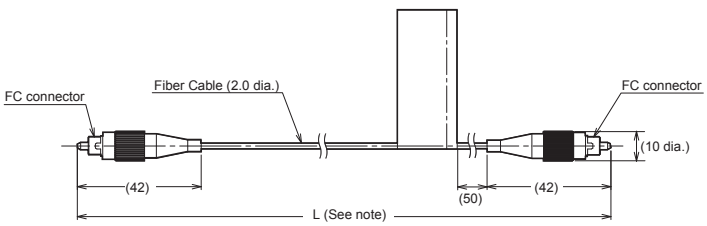
Controller

ZW-CE10T/-CE15T



Extension Fiber Cable

ZW-XF02R/-XF05R/-XF10R/-XF20R/-XF30R



Note: The following table lists cable lengths per models.

Model	Cable length	L
ZW-XF02R	2 m	2,000±20
ZW-XF05R	5 m	5,000±50
ZW-XF10R	10 m	10,000±100
`ZW-XF20R	20 m	20,000±200
ZW-XF30R	30 m	30,000±300

Related Manuals

Man.No.	Model number	Manual
Z332	ZW-CE1□T	Displacement Measurement Sensor ZW-CE1□T Series User's Manual

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